

MATH 208 C — MIDTERM 2 — Autumn 2022

NAME: Solutions

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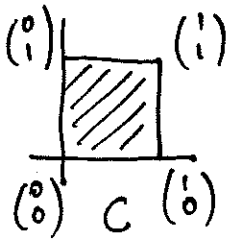
- (1) clearly in CAPITAL LETTERS,
- (2) exactly on the line above,
- (3) use the name you are registered under for this class.

- (1) Please put away all phones and earphones in your bag.
- (2) There are 4 problems.
- (3) Show all of your work and justify your answers.
- (4) Write clearly.

- (1) (a) Let C be the unit square in \mathbb{R}^2 with corners $(0, 0)$, $(1, 0)$, $(0, 1)$, $(1, 1)$. What is the image of C under the linear transformation $T(x) = Ax$ where

$$A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix} ?$$

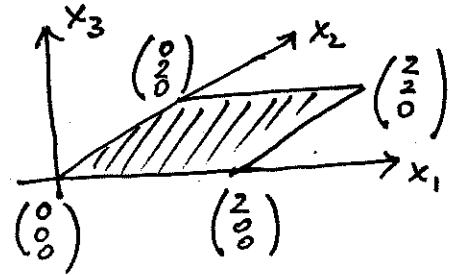
Draw a picture of the image and mark everything clearly.



$$T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} \quad T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$

$\therefore C$ goes to the square in \mathbb{R}^3 w/

corners $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix}$



since $T\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$
for any linear transformation

- (b) Write down the linear transformation that will take C and first apply T to it and **then** reflect the image of C under T across the (x_2, x_3) -plane.

The transformation should be written in full with domain, codomain and matrix. The matrices in the composition must be written out but you don't need to multiply them out.

Let $R: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be reflection across (x_2, x_3) -plane.

$$\text{Then } R\left(\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}\right) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ since } \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \\ \text{but } e_2 \mapsto e_2 \quad e_3 \mapsto e_3$$

The composed transformation is $R \circ T$

$$R \circ T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

(2) (a) Is the following a linear transformation? Give reasons for your answer.

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \\ \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} 2x + y \\ x + 1 \end{pmatrix}$$

Ans 1 $T\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \therefore T$ is not a linear transf.

Ans 2 $T\left(c\begin{pmatrix} x \\ y \end{pmatrix}\right) = T\left(\begin{pmatrix} cx \\ cy \end{pmatrix}\right) = \begin{pmatrix} c(2x+y) \\ cx+1 \end{pmatrix} \neq c T\left(\begin{pmatrix} x \\ y \end{pmatrix}\right)$

Ans 3: $T\left(\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}\right) = \cancel{T\left(\begin{pmatrix} x_1 \\ y_1 \end{pmatrix}\right) + T\left(\begin{pmatrix} x_2 \\ y_2 \end{pmatrix}\right)} T\left(\begin{pmatrix} x_1+x_2 \\ y_1+y_2 \end{pmatrix}\right) = \begin{pmatrix} 2x_1+y_1 + 2x_2+y_2 \\ x_1+x_2+1 \end{pmatrix}$
 $\neq T\left(\begin{pmatrix} x_1 \\ y_1 \end{pmatrix}\right) + T\left(\begin{pmatrix} x_2 \\ y_2 \end{pmatrix}\right)$

(b) Is the following a vector space? Give reasons for your answer.

$$S = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} : y = x^2 \right\}.$$

No: A point in S looks like $\begin{pmatrix} x \\ x^2 \end{pmatrix}$

for $c \in \mathbb{R}$ $c\begin{pmatrix} x \\ x^2 \end{pmatrix} = \begin{pmatrix} cx \\ cx^2 \end{pmatrix}$ but $cx^2 \neq (cx)^2$

So this set fails to be closed under scalar multⁿ.

- (3) Let T be the linear transformation such that $T(x) = Ax$ where A and its echelon form B are shown below.

$$A = \begin{bmatrix} 1 & 3 & -1 \\ 2 & 0 & 4 \\ -1 & 6 & -8 \end{bmatrix} \quad B = \begin{bmatrix} \textcircled{1} & 3 & -1 \\ 0 & \textcircled{1} & -1 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{pivot}$$

- (a) Compute a basis for the kernel of T .

$$\text{kernel}(T) = \text{nullsp}(A) = \text{nullsp}(B)$$

$$\text{Solve } Bx = 0 \quad x_2 = x_3 \quad x_1 = -3x_2 + x_3 = -2x_3$$

$$\therefore \text{Null}(B) = \left\{ \begin{pmatrix} -2s \\ s \\ s \end{pmatrix} : s \in \mathbb{R} \right\} \Rightarrow \text{basn of } \text{kernel}(T) \\ = \left\{ \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix} \right\}$$

- (b) Compute a basis for the range of T .

$\text{range}(T) = \text{colsp}(A)$. The ^A LI cols of A correspond to the pivot cols of B

$$\therefore \text{basn of } \text{range}(T) = \left\{ \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 6 \end{pmatrix} \right\}$$

- (c) Is T invertible? If yes, compute T^{-1} . If not, say why not.

No since T is invertible $\Leftrightarrow A$ is invertible

$\Leftrightarrow A$ can be row reduced to I

But B shows that the reduced echelon form of A cannot be I .

- (4) In the following questions, all transformations must be written fully with domain, codomain and matrix. Let

$$S = \left\{ \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} : \begin{array}{l} x + 2y + 3z - w = 0 \\ -z + w = 0 \end{array} \right\}.$$

- (a) What is the dimension of S ?

dimension of S is 2 since it is the intersection of 2 3d planes in \mathbb{R}^4 . Alternately there are 2 free vars in the system

- (b) Find a linear transformation P such that $S = \text{kernel}(P)$.

$$P: \mathbb{R}^4 \longrightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \mapsto \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$

$$\text{kernel}(P) = \text{nullsp} \left(\begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \right) = S$$

- (c) Find a linear transformation Q such that $S = \text{range}(Q)$.

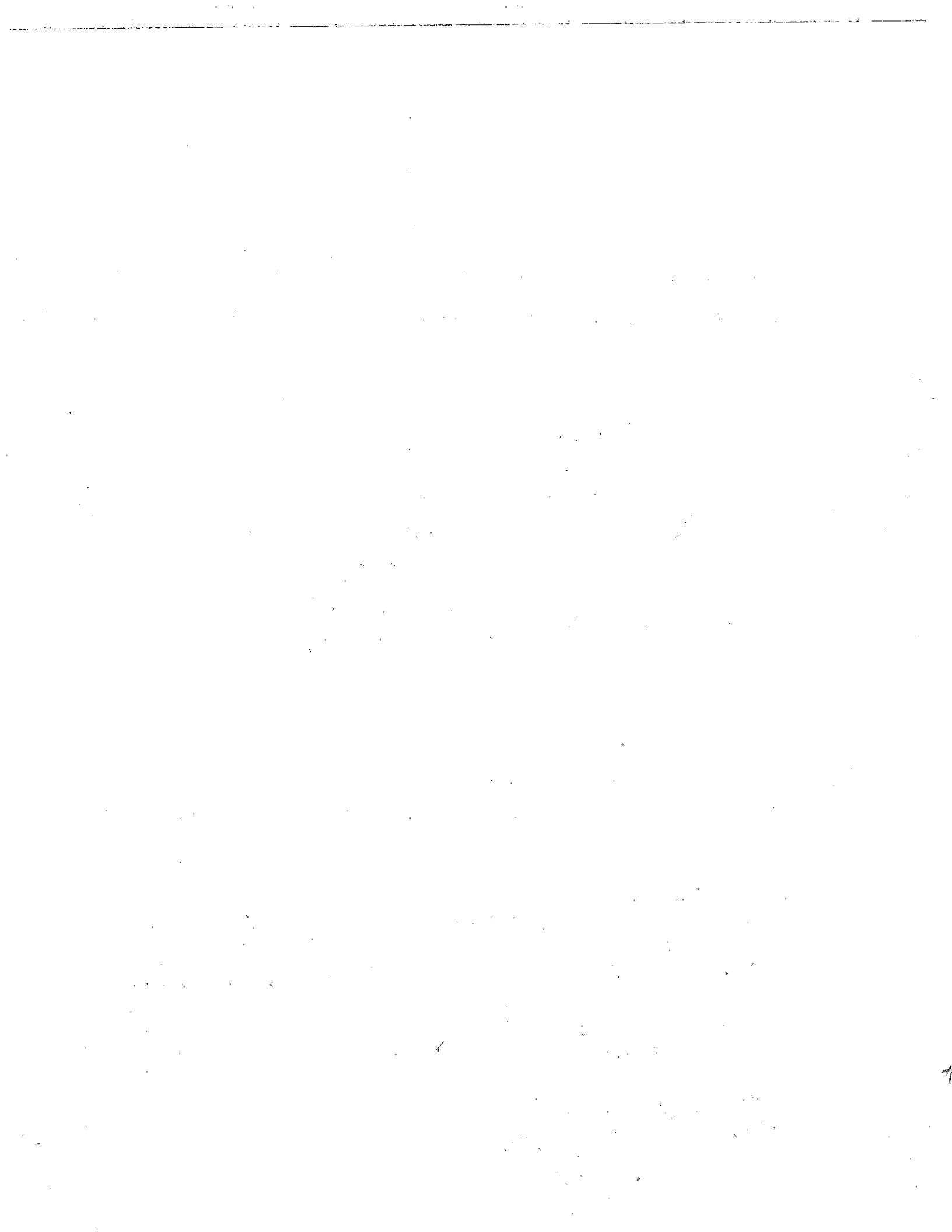
Solve the eq^{ns}:

$$\begin{aligned} z &= w \\ x &= -2y - 3z + w = -2y - 3w + w \\ &= -2y - 2w \end{aligned}$$

$$S = \left\{ \begin{pmatrix} -2s - 2t \\ s \\ t \\ t \end{pmatrix} : s, t \in \mathbb{R} \right\} = \text{Span} \left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}$$

$$Q: \mathbb{R}^2 \longrightarrow \mathbb{R}^4$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{bmatrix} -2 & -2 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$



MATH 208 D — MIDTERM 2 — Autumn 2022

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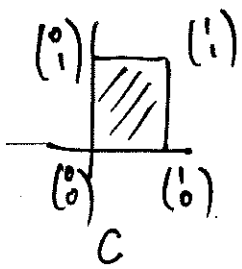
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- (1) (a) Let C be the unit square in \mathbb{R}^2 with corners: $(0,0), (1,0), (0,1), (1,1)$. What is the image of C under the linear transformation $T(x) = Ax$ where

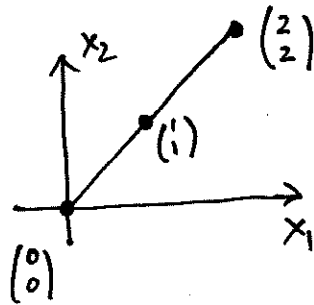
$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}?$$

Draw the image and mark it clearly.



$$\therefore T\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\therefore T(C) = \text{line segment in } \mathbb{R}^2 \text{ with end pts } \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ and } \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$



line segment in \mathbb{R}^2
with end pts $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 2 \\ 2 \end{pmatrix}$

- (b) Write down the linear transformation that will first apply T to C and then rotate the image of C under T by 90 degrees in the clockwise direction. The transformation must be written in full with domain, codomain and matrix. The matrices in the composition must be written out but you don't need to multiply them out.

Let $R: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the rotation matrix

then
$$R\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

The compound transformation is $R \circ T$

$$R \circ T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

- (2) (a) Is there any value of a for which the following is a linear transformation? If yes, find them all. If not, say why not.

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x+y \\ a+1 \end{pmatrix}$$

T must send $\begin{pmatrix} 0 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$T\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ a+1 \end{pmatrix} \quad \therefore a = -1 \text{ is needed.}$$

Then $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x+y \\ 0 \end{pmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad \text{is a lin. trans.}$$

- (b) Is the following a vector space? Give reasons for your answer.

$$S = \{x \in \mathbb{R}^3 : Ax = x\}.$$

Yes Check the 3 properties.

$$\textcircled{1} A\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \therefore \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in S$$

$$\textcircled{2} Ax_1 = x_1 \quad Ax_2 = x_2 \quad \therefore A(x_1 + x_2) = x_1 + x_2$$

for $x_1, x_2 \in S$

$$\textcircled{3} \text{ If } x \in S, c \in \mathbb{R} \quad Ax = x \Rightarrow Acx = cAx = cx.$$

Alternately $Ax = x \Leftrightarrow Ax = Ix \Leftrightarrow (A-I)x = 0$

$$S = \left\{ x \in \mathbb{R}^3 : (A-I)x = 0 \right\} = \text{Null}(A-I) \text{ which is a subspace.}$$

(3) Consider the matrix:

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 2 & 0 & -2 \\ -1 & 6 & 7 \end{bmatrix}.$$

(a) Does A have an inverse? If yes, compute it. If no, explain why.

$$\begin{bmatrix} 1 & 3 & 2 \\ 2 & 0 & -2 \\ -1 & 6 & 7 \end{bmatrix} \xrightarrow{\substack{R_2 \leftarrow R_2 - 2R_1 \\ R_3 \leftarrow R_1 + R_3}} \begin{bmatrix} 1 & 3 & 2 \\ 0 & -6 & -6 \\ 0 & 9 & 9 \end{bmatrix} \xrightarrow{\substack{R_2 \leftarrow -\frac{1}{6}R_2 \\ R_3 \leftarrow \frac{1}{9}R_3}} \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

A

A cannot be reduced to I so A is not invertible.

(b) Compute a basis for the range of the transformation $T(x) = Ax$. Explain.

range $(T) = \text{colsp}(A)$. Looking at B the 1st, 2nd cols of A are LI

$$\text{basn of range}(T) = \left\{ \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 6 \end{pmatrix} \right\}$$

(c) What is meant by the nullity of A and what is it in this case? Explain.

$$\text{nullity}(A) = \dim \text{nullsp}(A)$$

In this case A has 3 cols \cdot rank $(A) = 2$ by (b)

$$\therefore \text{Nullity}(A) = 3 - 2 = 1.$$

(4) Consider the set $S = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} : ax_1 + bx_2 = 0 \right\}$ where $a \neq 0$ and $b \neq 0$.

(a) Find a linear transformation T such that $S = \text{kernel}(T)$. Write it completely, with domain, codomain, matrix etc.

$$\text{kernel}(T) = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} : ax_1 + bx_2 = 0 \right\}$$

$$T: \mathbb{R}^2 \longrightarrow \mathbb{R}^1$$
$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \longmapsto \begin{bmatrix} a & b \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

(b) Express S as a span. Solve $ax_1 + bx_2 = 0$

$$S = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -b/a x_2 \\ x_2 \end{pmatrix} \right\} = \left\{ \begin{pmatrix} -b/a s \\ s \end{pmatrix} : s \in \mathbb{R} \right\}$$
$$= \text{Span} \left\{ \begin{pmatrix} -b/a \\ 1 \end{pmatrix} \right\}$$

(c) Find a linear transformation U such that $S = \text{range}(U)$. Write it completely, with domain, codomain, matrix etc.

$$\text{range}(U) \text{ must be } \text{Span} \left\{ \begin{pmatrix} -b/a \\ 1 \end{pmatrix} \right\} = \text{colsp}(\text{matrix of } U)$$

$$U: \mathbb{R}^1 \longrightarrow \mathbb{R}^2$$
$$x \longmapsto \begin{bmatrix} -b/a \\ 1 \end{bmatrix} x$$

